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10/813,824

March 31, 2004

Application Number

Filing Date

	FURIVI		First Name d Investor	K-Li- D	0-16			
(to be used for	all correspondence after initial	filina)	First Named Inventor	Kelvin P. Self				
(10 20 0300 107	an correspondence and initial	illing)	Art Unit	3672	3672			
		Examiner Name Daniel P. Step		Stephe	henson			
Total Number of Pages in This Submission		16	Attorney Docket Number	2380-544				
ENCLOSURES (Check all that apply)								
Fee Transmittal Form		Drawing(s)				vance Communication nological Center (TC)		
Fee Attached		Licensing-related Papers					ommunication to Board s and Interferences	
Amendment/Reply		☐ Pe	Petition :				ommunication to TC lotice, Brief, Reply Brief)	
After Final			Petition to Convert a Provisional Application			Proprietar	y Information	
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Extension of Time Request		□ Те	☐ Terminal Disclaimer			Other End Identify be	elosure(s) (please elow)	
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under 37 St IV 1.32 St 1.33								
SIGNATURE OF APPLICANT, ATTORNEY, OR AGENT								
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Signature	for T. All							
Date May 1, 2006								
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Signature /		1. 4				Date	May 1, 2006	

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□ DESIGN ⊠ UTILITY PATENT

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

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Serial No: 10/813,824

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For: DIRECTIONAL REAMING

SYSTEM

Att'y Dkt. No.:

2380-544

Art Unit:

3672

Examiner:

Daniel P.

Stephenson

Customer No.:

28839

Mail Stop Amendment Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450

AMENDMENT AND RESPONSE TO OFFICE ACTION MAILED MARCH 22, 2006

Applicants respectfully requests that the above application be amended as follows:

In the Specification

Please replace paragraph 0117 with the following:

[0117] With continued reference to FIG. 17, the movable pipe positioning arm 508 may be pivotally supported at one end, for example by way of a universal joint 526 (hereafter referred to as a "u-joint") or other variable angularity-allowing devices. Since a u-joint does not limit angular motion to a single plane, two arm positioners 510 supportingly arranged a quarter circle (90°) apart around its axis may be utilized to stabilize and also control the deployment direction of positioning arm 508. (The partially sectional view of FIG. 17 prevents a second positioner being shown.) The point of pivotal support provided by u-joint 526 lies approximately on the central axis of borehole 42, and is preferably axially located within the envelope of surface 502. Furthermore, the point of support is held in fixed axial relationship to borehole enlarging and engaging surface 502 while being rotationally uncoupled from it. This may be